

























1-axis G-sensor				
	Hollow proof-mass			
Measurement Range (G)	0.3~10			
Sensitivity (mV/G)	3.95			
Resonant Freq. (kHz)	5.83			
Nonlinearity (%)	2.75			
Cross-axis sensitivity_Y (%)	1.05			
Cross-axis sensitivity_Z (%)	<1			
Sun, and Fang, <i>IEEE</i> Sun, and Fang, <i>Sens. A</i>	Sensors, 2006 ctuators A, 2008	MDL		













































	Tilt Sensor w Pick-place Mass			
500		Rota	te table	
	Specifications	W/O bulk ball	With bulk ball	
	Proof mass (ng)	1.72	62.14	
	Linear range (°)	0 ~ 45	0 ~ 45	
	Sensitivity (mV/°)	0.41	1.41	
	Resolution (°)	1	0.1	
	Non-linearity (%)	7.6	2.3	
	Chang, and Fan	ng, IEEE Transd	<i>ucers</i> , 2011	MDL







Pure oxide CMOS device Image: State of the s				
Sensing-axis	X-axis	Y-axis	Z-axis	ן
Measurement Range (G)		±2		
Sensitivity (mV/G)	105.2	127.4	57.7	
Non-linearity (%)	1.01	0.52	2.43	
Noise (mG/sqrtHz)	0.4	0.21	0.94	
Cross-axis sensitivity _X(%)		1.57	6.41	
Cross-axis sensitivity _Y(%)	1.05	/	6.07	
Cross-axis sensitivity _Z (%)	2.86	1.65		
Liu, and Fang,	IEEE MEM	S, 2012		MDL











3-axis G-sensor					
"WWWAN"				atan	
Sing	le proof-mass 3-axis G-sensor	.18µm CM	OS process	s (0.4mm×0	.4mm)
	Sensing-axis	X-axis	Y-axis	Z-axis	
	Measurement Range (G)	0.01~1	0.01~1	0.01~1	
	Sensitivity (mV/G)	14.2	14.6	8.0	
	Non-linearity (%)	3.0	1.5	1.8	
	Noise (mG/sqrtHz)	1.9	2.9	3.4	
	Cross-axis sensitivity _X(%)		8.1	2.3	
	Cross-axis sensitivity _Y(%)	7.4		8.0	
	Cross-axis sensitivity _Z (%)	5.7	6.4		
Tsai, and Fang, IEEE Transducers, 2011					MDL





























































